

## Maxwell Equation (Differential Form)

First

$$I) \nabla \cdot D = \rho \quad (\text{Gauss law of Electrostatics})$$

OR

$$II) \nabla \cdot E = \rho / \epsilon_0 \quad (\text{Using } D = \epsilon_0 E)$$

Second

$$II) \nabla \cdot B = 0 \quad (\text{Gauss law of Magnetostatics})$$

Third

$$III) \nabla \times E = -\frac{dB}{dt} \quad (\text{Faraday law})$$

Fourth

$$IV) \nabla \times B = \mu_0 \left( J + \frac{dD}{dt} \right) \quad (\text{Modified Ampere circuital law})$$

OR

$$\nabla \times H = \left( J + \frac{dD}{dt} \right) \quad (\text{Using } B = \mu_0 H)$$

## Maxwell Equation (Integral Form)

First

$$I) \oint E \cdot ds = \frac{q}{\epsilon_0}$$

Second

$$II) \oint B \cdot ds = 0$$

Third

$$III) \oint E \cdot dl = -\frac{d\phi_B}{dt}$$

Fourth

$$IV) \oint B \cdot dl = \mu_0 \left( J + \frac{dD}{dt} \right) \cdot ds$$

where

- D - Displacement or Electric Displacement  
(Coulomb/m<sup>2</sup>)
- P - Charge Density (Coulomb/m<sup>3</sup>)
- B - Magnetic Induction (Wb/m<sup>2</sup>)  
or Flux density
- H - Magnetic Field Intensity (Amp/m)
- J - Current Density (I/A) (Current/Ampere)

## First Maxwell Equation:-

$$\nabla \cdot E = \rho / \epsilon_0$$

### Physical significance:-

- It is based on Gauss law of Electrostatics
- Net Electric Flux through a closed surface is equal to  $\frac{1}{\epsilon_0}$  the total charge enclosed by the surface.

$$\nabla \cdot E = \frac{q}{\epsilon_0}$$

$$\oint_S E \cdot ds = \frac{1}{\epsilon_0} \int_V q \cdot dv \quad \text{--- (1)}$$

(Differential form)

(Integral form)

- It relates Electric Flux with charge.
- Charge acts as a source or sink for the line of Electric force

Derivation:- Consider a surface bounded by a volume  $V$  in a medium having charge density as  $\rho$ .

Then

$$q = \int_V \rho \cdot dv$$

Using (1) Gauss law of Electrostatics we have

$$\oint E \cdot ds = \frac{q}{\epsilon_0}$$

Substituting  $q = \int_V \rho \cdot dv$

Then

$$\oint E \cdot ds = \frac{1}{\epsilon_0} \int_V \rho \cdot dv \quad \text{--- (2)}$$

From Gauss theorem we have -

$$\oint_S \mathbf{E} \cdot d\mathbf{s} = \int_V (\nabla \cdot \mathbf{E}) dV \quad \text{--- (2)}$$

(Note Gauss divergence theorem converts Surface Integral to Volume Integral)

Equating (2), (3) we get.

$$\int_V (\nabla \cdot \mathbf{E}) dV = \frac{1}{\epsilon_0} \int_V \rho dV$$

$$\int_V \left( \nabla \cdot \mathbf{E} - \frac{\rho}{\epsilon_0} \right) dV = 0$$

$$\Rightarrow \boxed{\nabla \cdot \mathbf{E} = \rho / \epsilon_0}$$

↓  
Maxwell (1) Equation.

~~Maxwell's Second Equation!~~

## Maxwell's Second Equation:-

$$\nabla \cdot \mathbf{B} = 0$$

### Significance:-

- It is based on Gauss law of Magnetostatics.
- It states that magnetic flux through any closed surface is zero

Differential form

$$\nabla \cdot \mathbf{B} = 0$$

Integral form

$$\oint \mathbf{B} \cdot d\mathbf{s} = 0$$

- Time independent Equation
- Magnetic flux is zero
- According to this Equation, isolated magnetic poles don't exist.

Derivation:- we have by Gauss law of Magnetostatics

$$\oint \mathbf{B} \cdot d\mathbf{s} = 0 \quad \text{--- (1)}$$

By Gauss divergence theorem we have-

$$\oint \mathbf{B} \cdot d\mathbf{s} = \int_V (\nabla \cdot \mathbf{B}) dV \quad \text{--- (2)}$$

(Note:- By Gauss divergence theorem we have surface integral equal to volume integral)

Equating (1), (2)

$$\int_V (\nabla \cdot \mathbf{B}) dV = 0$$

$$\boxed{\nabla \cdot \mathbf{B} = 0} \rightarrow \text{Maxwell's Second Equation}$$

## Maxwell's Third Equation:-

$$\nabla \times \underline{E} = -\frac{dB}{dt}$$

### Significance:-

→ This Equation represent Faraday law of Electro-Magnetic Induction.

Differential form

$$\nabla \times \underline{E} = -\frac{dB}{dt}$$

Integral form

$$\oint \underline{E} \cdot d\underline{l} = -\frac{d\phi}{dt}$$

- It is time dependent Equation.
- Relates space variation of  $\underline{E}$  with variation of  $B$
- Time variation of Magnetic field generates Electric field.
- Negative sign justify Lenz law.

Derivation:- we have by Faraday law.

$$\begin{aligned} \oint \underline{E} \cdot d\underline{l} &= -\frac{d\phi}{dt} \\ &= -\frac{d(\underline{B} \cdot d\underline{S})}{dt} \quad (\phi = \underline{B} \cdot d\underline{S}) \end{aligned} \quad \text{--- (1)}$$

By Stokes theorem we have.

$$\oint \underline{E} \cdot d\underline{l} = \int_S (\nabla \times \underline{E}) \cdot d\underline{S} \quad \text{--- (2)}$$

Equating (1) (2)

$$\int_S (\nabla \times \underline{E}) \cdot d\underline{S} = -\frac{d}{dt} \int_S \underline{B} \cdot d\underline{S}$$

$$\int_S (\nabla \times \underline{E}) \cdot d\underline{S} = -\frac{d}{dt} \int_S \underline{B} \cdot d\underline{S}$$

$$\Rightarrow \boxed{\nabla \times \underline{E} = -\frac{dB}{dt}} \quad \text{--- Maxwell Third Equn}$$